

## 6 Quick Set-up

At delivery status the JIVE ESC is set at **APM** (Auto-Programming-Mode). It will adapt itself to the throttle positions of the RC.

1. Switch on Tx - set throttle control to off
2. Switch on RX
3. Connect battery to JIVE ESC
4. Give 1s full throttle or start with full throttle
5. Ready

If the motor fails to start, disconnect battery and switch Tx option "reversion of rotation" on or off.

**! In all other modes the throttle position will be programmed and fixed and not learnt with every start.**

## 7 Programming

Mode		Throttle positions fixed	Brake	Proportional Brake	Separate Motor-Off-Position	Under voltage disconnection	Over temperature protection	Current limiting	Slow down	RPM control
1	APM	-	-	-	-	✓	✓	✓	-	-
2	Glider	✓	✓	-	✓	✓	✓	✓	-	-
3	Motor plane / boat	✓	-	-	-	-	✓	✓	✓	-
4	Helicopter 1	✓	-	-	-	-	✓	✓	✓	✓
5	Competition Mode	✓	✓	-	-	-	-	-	-	-
6	RC Car	✓	-	✓	✓	✓	✓	✓	-	-
7	Reverse Motor Rotation	Reverses RPM direction of the motor								
8	Motor plane F3A brake	✓	✓	-	-	-	✓	✓	✓	-
9	LiPo	Activates under voltage disconnection for LiPo batteries								
10	KSA	Activates <u>K</u> ONTRONIK <u>S</u> pecial <u>A</u> pplication mode								
11	Helicopter 2	✓	-	-	-	-	✓	✓	✓	✓