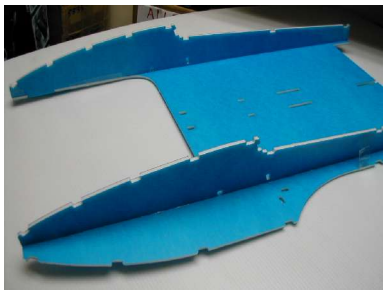
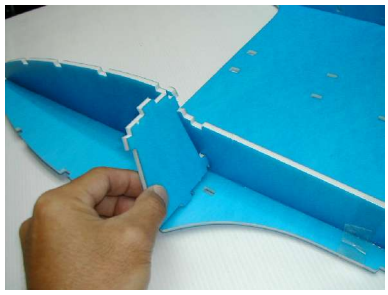
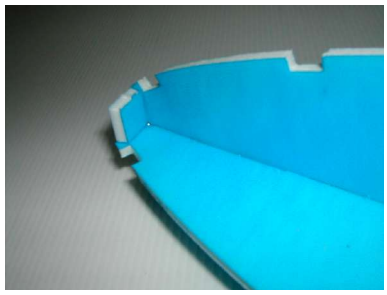
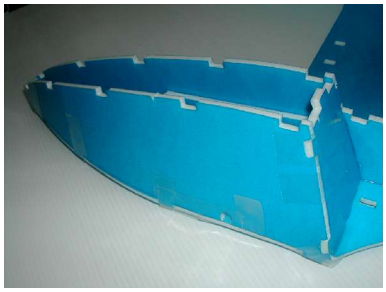
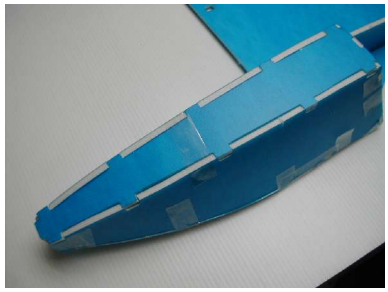




1) Build the hull with epoxy

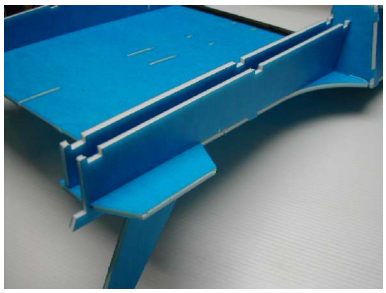
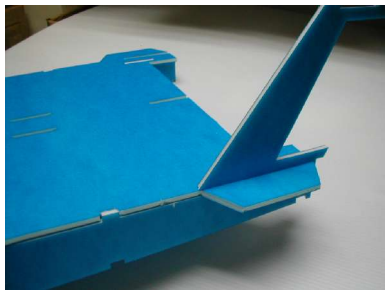
2) Fix the reinforce carbon tube

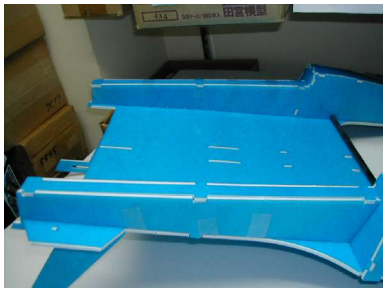
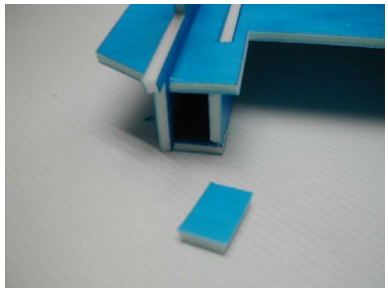
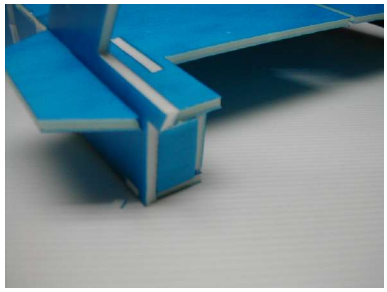
3) Dash step of the hull (front part)

4) Reinforce Carbon tube between left and right hull

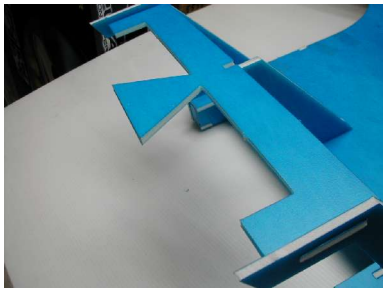
5) Finished hull (front part)

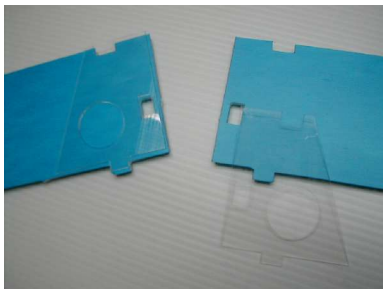

6) Fix the hull (rear part)

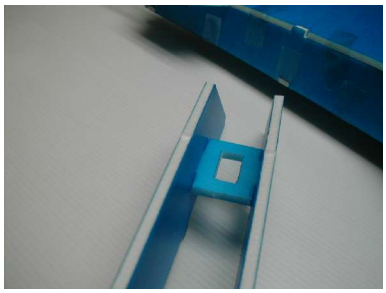
7) Use epoxy to fill the gaps around the hull



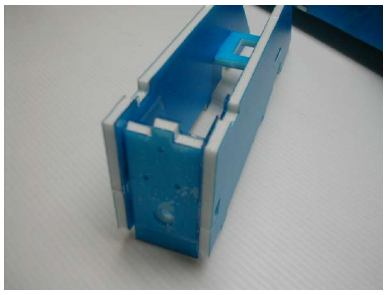
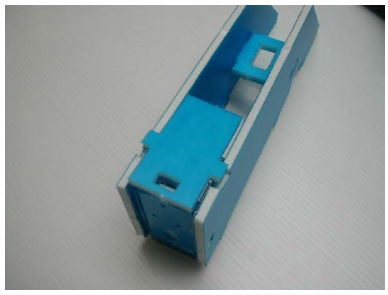
8) Upper stabilizer



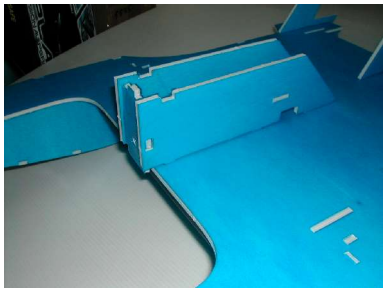
9) Fix the plastic reinforce plate inside the control room



10)Rudder servo mount

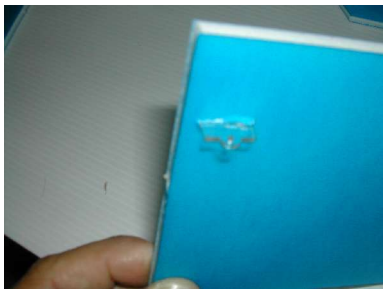
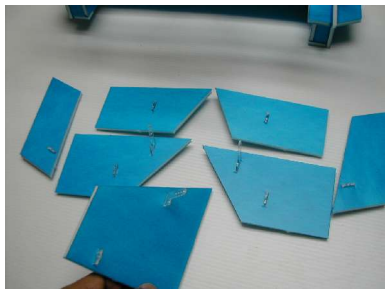



11)Motor mount

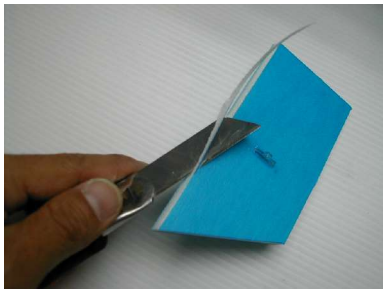
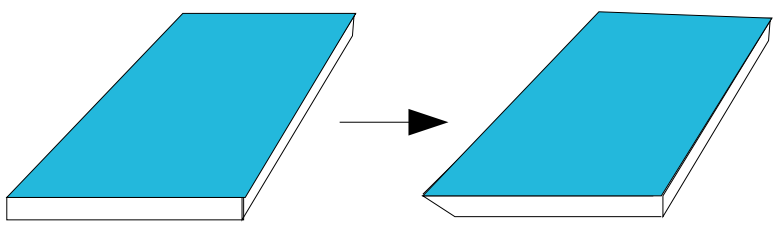


12)Fix the motor mount on the deck floor. The position of the control room can be change in order to achieve the best balancing point in flight, depending on the weight of the R/C equipments. In the above example, the room was positioned approx. one inch forward.

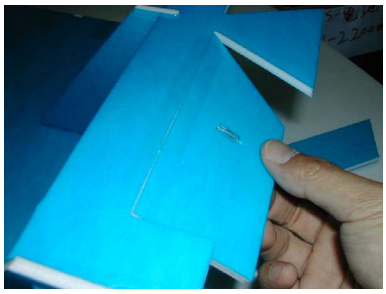
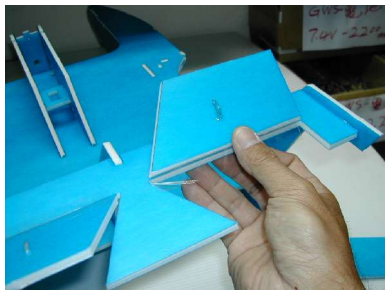
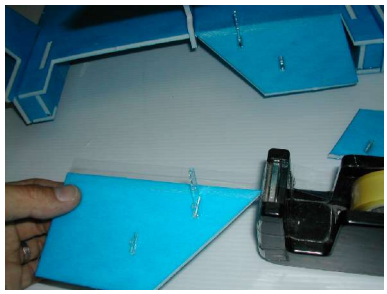
13)Remove the protection film of control horn

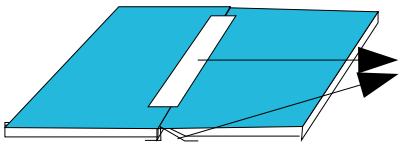



14)Use epoxy to glue the control in all control surface

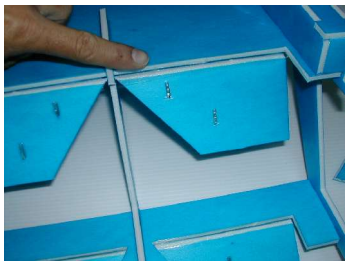



15)Use a knife to cut the control surface at an 45 degrees angle

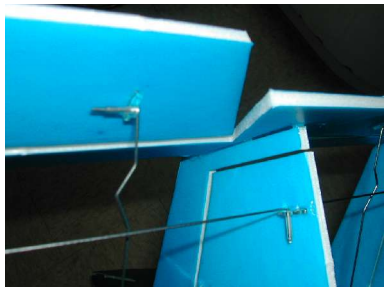


18)Use adhesive tape to hinge the control surface



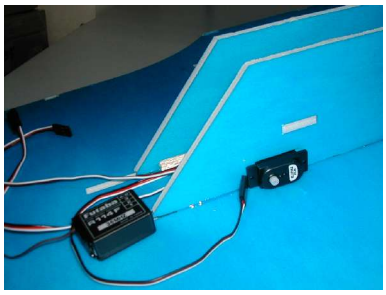
17)Make sure the control surface can move 30 degrees up and down

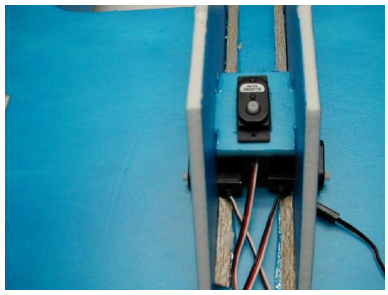


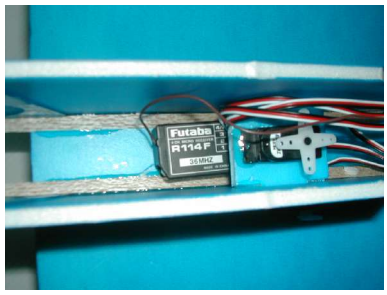


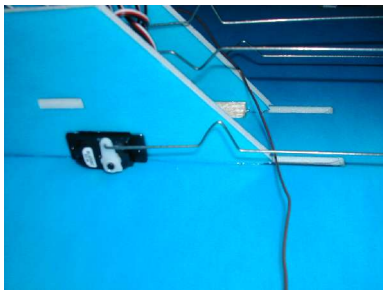
18)Join the push rod between upper and lower stabilizer (parallel)

19)3 x micro servo and 1 x micro receiver



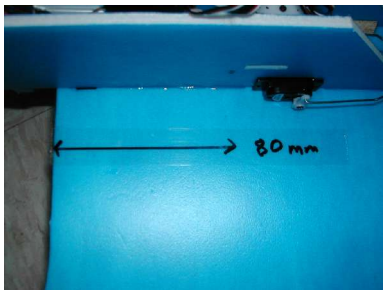




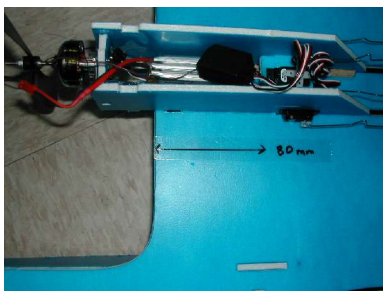


20)Install the servo as shown

21)Bend the push rod for adjustment as shown



22)C. of G. Located in 80mm from the leading edge



23)Motor and ESC installed infront of the control room

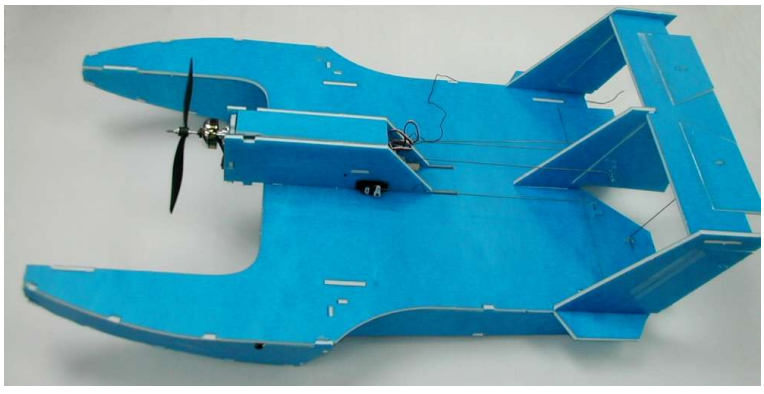
24)Set the control in elevon or delta wing

Turn Left

Turn Right

Ascend

Descend



Ready to Run and Fly!!!