

KK2.0 Version			Motor Layout:			Date:		
PI Editor			P Gain	P Limit	I Gain	I Limit		
	Roll (Ail)							
	Pitch (Ele)							
	Yaw (Rud)							
Mode Settings	Self Level		Link Roll Pitch		Auto Disarm		CPPM Enabled	
	AUX	Stick	Yes	No	Yes	No	Yes	No
Stick Scaling	Roll (Ail)		Pitch (Ele)		Yaw (Rud)		Throttle	
Misc. Settings	Minimum Throttle		Height Dampening		Height D. Limit		Alarm 1/10 Volt	
Self-Level Settings	P Gain		P Limit		ACC Trim Roll		ACC Trim Pitch	
Camera Stab Settings	Roll Gain		Roll Offset		Pitch Gain		Pitch Offset	
CPPM Settings	Roll (Ail)		Pitch (Ele)		Throttle		Yaw (Rud)	
Mixer Editor			CH1	CH2	CH3	CH4	CH5	CH6
	Throttle							
	Aileron							
	Elevator							
	Rudder							
	Offset							
	Type							
	Rate							



Notes:

Menu

1. PI Editor	6. Self-Level Settings	11. Mixer Editor
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3. Mode Settings	8. Sensor Test	13. Load Motor Layout
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5. Misc. Settings	10. CPPM Settings	15. Factory Reset